# User's manual for SM400DV4

#### PROCEDURE FOR INITIAL SETTING

- 1) When power put in, AC6P will be shown and becomes Automatic operation mode with "AUTO" indicator.
- 2) For initial stage of installation, Program Setting should be done. Press "DOWN" key in 3 seconds and a door will open while flickering "ACL" in Indicator.
- 3) It automatically calculates opening distance and completes door closing. Then Indicator show "AUTO" to say, it is ready to move in automatic mode.
- 4) Now press, "ESC/SAVE" key to save all data and escape a programming mode.

### PROCEDURE FOR PARAMETER ADJUSTMENTS

- 1) At auto mode, when press, "MODE" key, indicator shows, "CO". Then Now You can adjust up to, "C40" by "UP" key.
- 2) At each, "C0" to "C40" parameters, if you press, "MODE" key, You can see, present Data. Here you can adjust its values by scrolling them with UP/DOWN key. Once you set, you can escape by press, "MODE" key.
- 3) Once completed, You bring it down to "CO" and Press, "MODE" key. Then It comes to the "AUTO" model. All data will be saved by pressing, "ESC/SAVE" key.
- 4) If YOU DON'T Press, "ESC/SAVE" key, Data will go away without saving. Then all data will be returned to the previous data setting when power-off.
- 5) For defaults setting, Please Press, "UP" key in 3 seconds. Now indicator shows, "- - " and Data is all default setting.

## 2. Pattern setting table

Code	Explanation	Range(Basic)	Contents
C1	Slow speed time at early	10-1000(750)	Time reduces when it
	door opening phase		increases
C2	Speed at slow speed section at	20-200(40)	Speed increases
	early door opening phase		when it increases
СЗ	Tilt of opening acceleration	100-4000(600)	Drastic acceleration when it
			increases
C4	Maximum opening speed	100-1200(470)	Speed increases
			when it increases
C5	Tilt of opening deceleration	100-4000(350)	Emergency deceleration
			when it increases
C6	Distance of slow speed section at	5-50(25)	No slow speed section when it
	the end of door opening		increases
C7	Speed of slow speed section at	5-100(50)	Speed increases
	door opening phase in ending.		when it increases
C8	Torque in starting position of door	20-50(23)	Emergency stopping
	opening		when it increases
C9	Speed of slow speed at door	20-100(40)	Torque increases
	opening phase in ending.		when it increases
C10	Torque which maintains Stopping	10-50(25)	Torque increases
	status at the end of door opening		when it increases
C11	Torque of Jog	10-50(25)	Drastic acceleration when it
			increases
C12	Speed of Jog	50-200(135)	Speed increases
			when it increases
C13	Tilt of closing deceleration	100-4000(100)	Distance reduces when it
			increases
C14	Maximum closing speed	100-1200(320)	Reduces when it increases
C15	Tilt of closing acceleration	100-4000(300)	Speed increases
			when it increases
C16	Closing torque	10-50(25)	Delaying time reduces when
			it increases

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C17	Distance of slow speed section at	5-100(80)	Speed increases
	the end of door closing	, ,	when it increases
C18	Speed of slow speed section at	50-100(40)	Torque increases
	the end of door closing		when it increases
C19	Delaying time of stopping from the	100-5200(3800)	Speed increases
	end of closing sensor		when it increases
C20	Door Speed after closing sensor	5-200(20)	Reduces 밀립(?) status
	from the end of closing		
C21	Stopping torque at the end of	10-50(35)	Drastic acceleration when it
	closing		increases
C22	Slow speed torque at the end of	5-50(25)	Speed in case of disorder
	closing		
C23	Distance of turning in the reverse	10-1000(20)	Torque increases
	direction		when it increases
C24	Stopping torque at enforced door	10-50(25)	Distance of turning in the
	opening		reverse direction increases
			when it increases
C25	Duration time at enforced door	10-100(20)	
	opening	10 100(10)	
	9,000		
C27	Tilt of reopening acceleration in	100-4000(20)	
02,	reopening	100 1000(20)	
C28	Tilt of reopening deceleration in		
020	reopening		
C30	System deceleration ratio	10-100(30)	At 4 poles(47)
			middle speed 3 = slow speed
C33	System initialization		middle speed 5 – slow speed
000		initialization	
C36	Torque compensation max. speed.	2-200(40)	Speed increase if inceased
C37	Torque compensation max. speed	0-50(30)	
C46	Opening Instruction when a door	0-1 (0 - NON (1 - Operation)	
	is in intermediate Stop	operation)	
C50	Upon complete door closing,	0-3 ( 0 is to enable in door opening by enforced	
	Indicate operation status	closing torque.)	
		( 3 is to disable in door opening by enforced	
		closing torque.)	
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## 3. SM400D ERR code

Indication	Occasion	Check point	
Sr-t	over current	Check motor short, check electric leakage	
Er-b	OP/CL sensor do not work	Check OP, CL sensor	
	within 10 seconds		
S1-b	Motor go round more than	Check the fixed part of motor like belt	
	2times after checking OP/CL		
Er-p	The phase of motor rotation and	Rotation of motor and encoder phase C27 is	
	encoder is in different direction	adjustable	
Ec-s	When gauging door width,	Discordance of direction,	
	CL sensor is not detected for	Jogging operation	
	more than 10seconds		
Ео-е	Bad encoder	Jogging operation, change encoder	
Er-s	Simultaneous operation of	Door stop, Check sensor, Control CLEND, OPEND	
	CL/OP sensor		

